

Learning to estimate anthropometric measurements from partial 3D data

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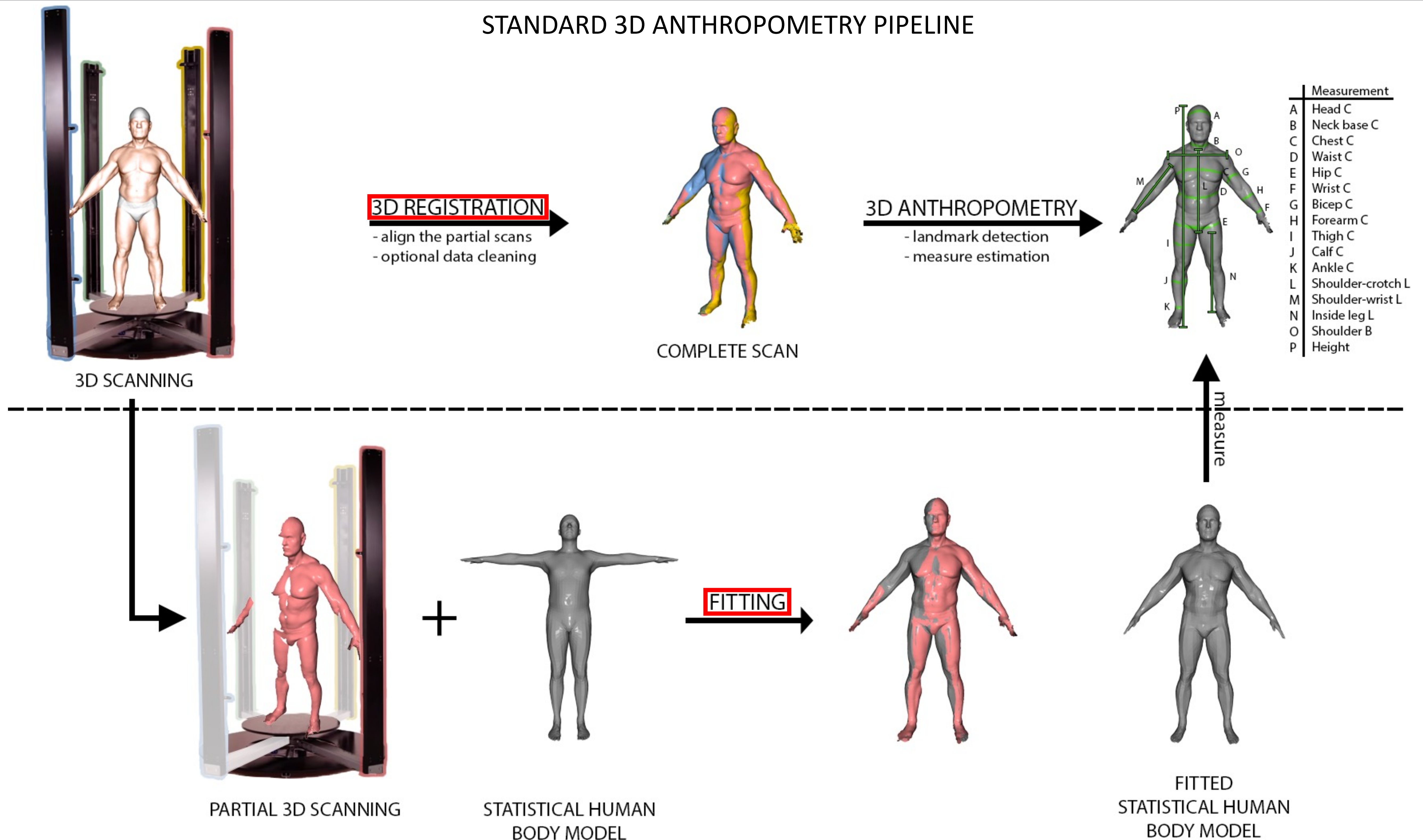
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STANDARD 3D ANTHROPOMETRY PIPELINE



3D Registration

Find the optimal rotation and translation that aligns two partially overlapping 3D scans.



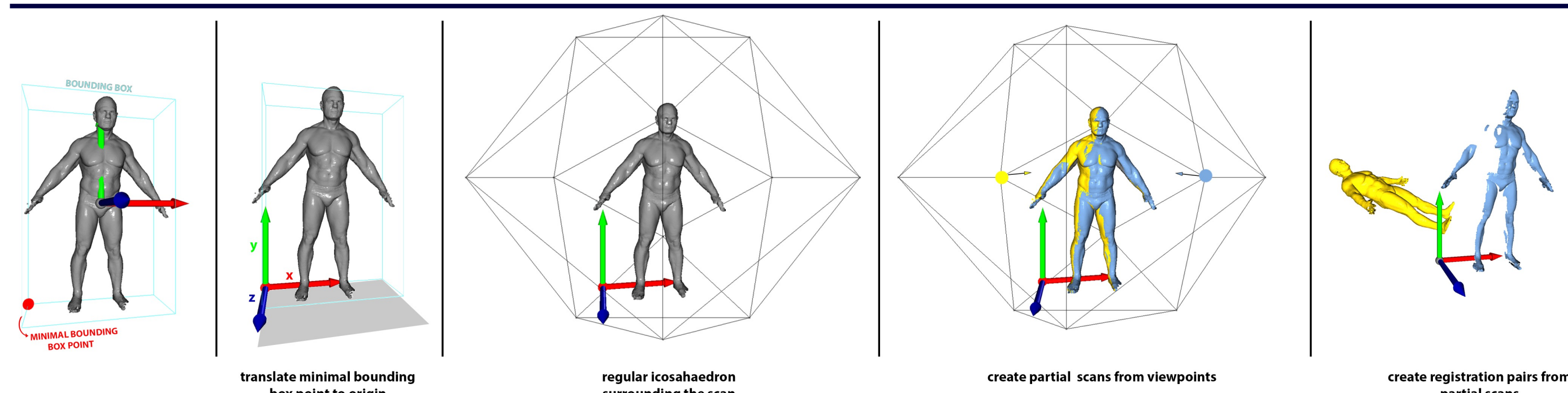
State-of-the-art limitations

- (a) Learning-based methods struggle with generalization [1]
- (b) 3D registration benchmarks suffer from low data variability [1]

(a) New baseline – Exhaustive Grid Search (EGS)

We propose a traditional method that exhaustively searches the rotation and translation spaces using the weighted cross-correlation.

(b) New benchmark – FAUST-partial (FP)

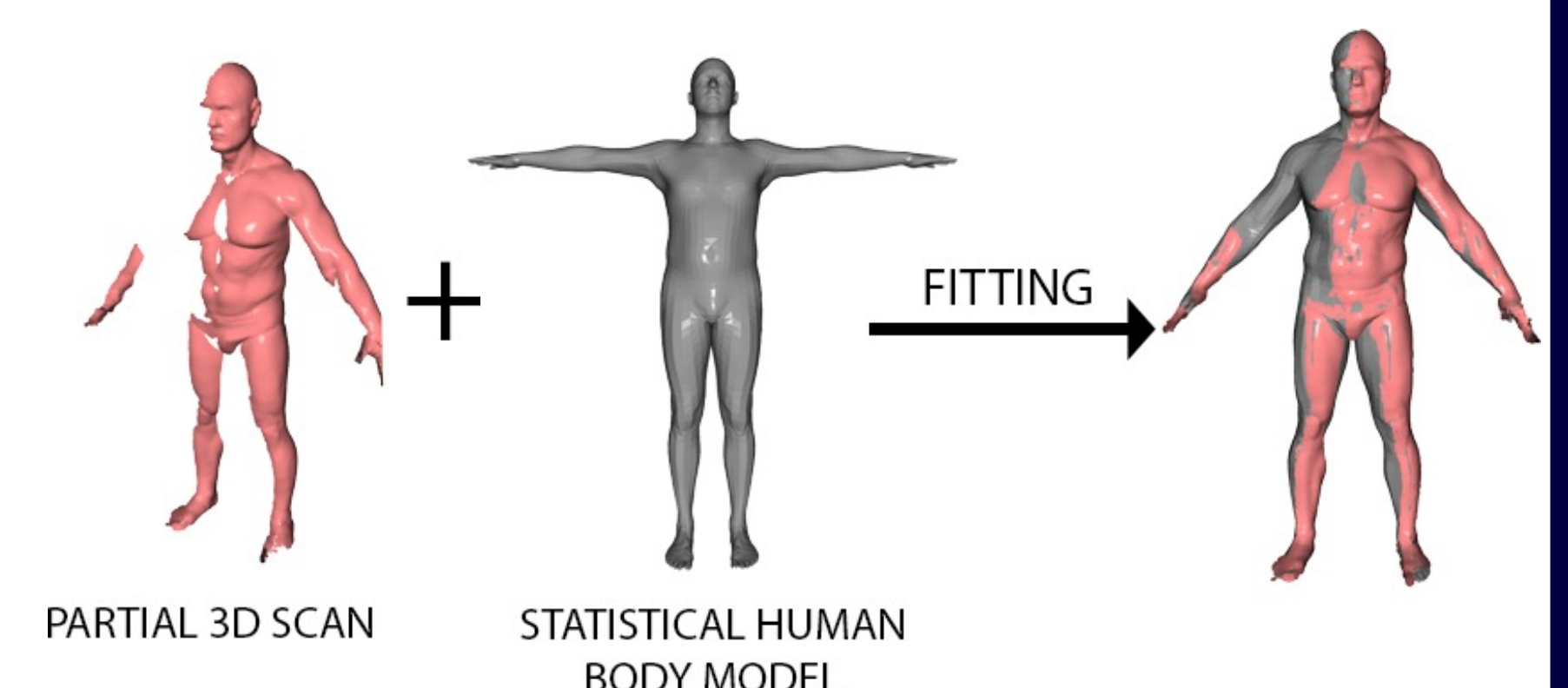


Dataset	FP - rotation			FP - translation			FP - overlap		
	easy	medium	hard	easy	medium	Hard	easy	medium	hard
FPFH+SC2-PCR	99.64	94.54	75.21	99.76	99.53	<u>99.58</u>	99.88	<u>84.70</u>	38.85
GeDi	99.76	99.94	99.41	99.47	<u>99.70</u>	99.70	<u>99.64</u>	75.40	8.70
FCGF+SC2-PCR	98.46	91.93	<u>85.77</u>	98.34	98.34	98.22	98.52	63.00	17.80
GeoTransformer	64.12	55.93	47.75	66.25	64.29	64.18	63.94	22.07	2.64
EGS	<u>99.64</u>	<u>97.92</u>	78.00	<u>99.70</u>	99.82	98.81	99.47	88.06	<u>37.06</u>

Table 1. Registration recall (%) results on the FAUST-partial benchmark.

Fitting

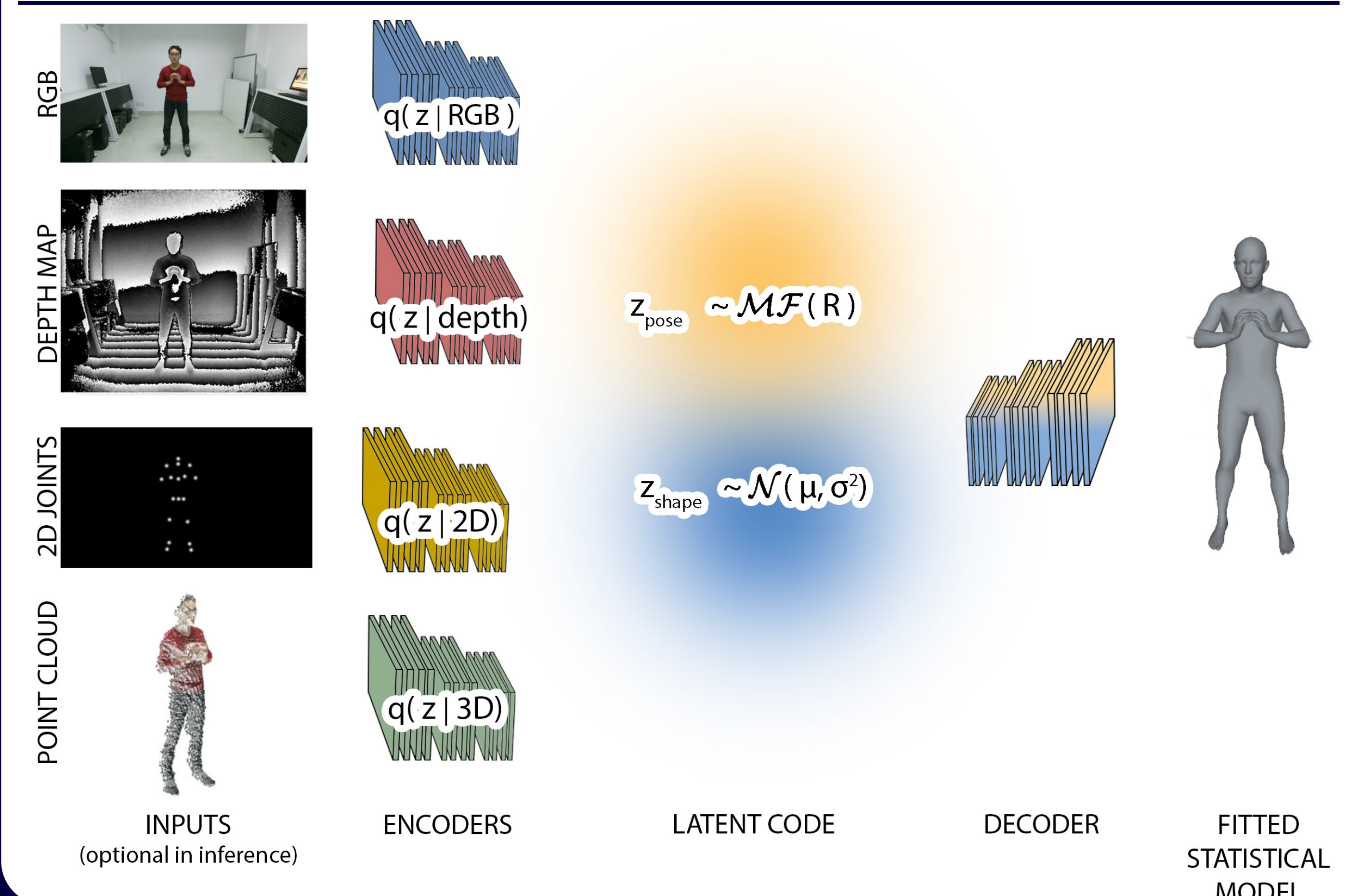
Fit a statistical human body model to a partial 3D scan so that it best describes the shape and pose of the input point cloud.



State-of-the-art limitations

- (c) Need landmarks [2] or struggle with *rare* poses and shapes [3]

(c) New cross-modal probabilistic approach (future work)



Acknowledgments

This work has been supported by the Croatian Science Foundation projects IP-2018-01-8118 and DOK-2020-01.



References

- [1] Bojanić et al.: Deep Learning vs. Traditional 3D Registration: A Featureless 3D Registration Baseline
- [2] Pishchulin et al.: Building statistical shape spaces for 3D human modeling
- [3] Guanze et al.: VoteHMR: Occlusion-Aware Voting Network for Robust 3D Human Mesh Recovery from Partial Point Clouds

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